

Knapsack problem—traditional dynamic programming

for $b := 0$ to B do $K[0, b] := 0$

for $i := 1$ to n

 for $b := 1$ to B

 if $w_i \leq b$ and $K[i - 1, b - w_i] + c_i > K[i - 1, b]$

$K[i, b] := K[i - 1, b - w_i] + c_i$

 else

$K[i, b] := K[i - 1, b]$

return $K[n, B]$

Running time: $O(nB)$

Knapsack problem—alternative dynamic programming

for $c := 0$ to C do $F[0, c] := \infty$

$F[0, 0] := 0$

for $i := 1$ to n

 for $c := 0$ to C

 if $c_i > c$ and $F[i - 1, 0] + w_i \leq F[i - 1, c]$

$F[i, c] := F[i - 1, 0] + w_i$

 else if $c_i \leq c$ and $F[i - 1, c - c_i] + w_i \leq F[i - 1, c]$

$F[i, c] := F[i - 1, c - c_i] + w_i$

 else

$F[i, c] := F[i - 1, c]$

return maximum c , for each $F[n, c] \leq B$

Running time: $O(n^2 \max\{c_i\})$

Definition: Approximation algorithm $A(x, \varepsilon)$ is a **polynomial-time approximation scheme (PTAS)** if for any constant $\varepsilon > 0$

$$A(x, \varepsilon) \leq (1 + \varepsilon)OPT(x) \quad (\text{min. problem})$$

$$\text{resp. } A(x, \varepsilon) \geq (1 - \varepsilon)OPT(x) \quad (\text{max. problem})$$

and its running time is polynomial with respect to $|x|$.

It is a **fully-polynomial-time approximation scheme (FPTAS)** if its running time is also polynomial with respect to $1/\varepsilon$.